WHAT IS CLAIMED IS:

1. A stabilized platform comprising:

a payload platform for supporting an article to be stabilized;

a base;

a stabilizing system connecting the payload platform to the base, the stabilizing system including at least two motors for rotating the payload platform with respect to the base about two perpendicular axes of rotation providing the payload platform with stabilization in two dimensions;

a first sensor package for determining motion of a vehicle on which the stabilized platform is mounted in two perpendicular directions;

a second sensor package including at least one level sensor fixed to the payload platform; and

a control system for stabilizing the platform based on information provided by the first sensor package and the second sensor package.

2. The stabilized platform of Claim 1, wherein the control system compensates for errors in the first sensor package using information obtained from the second sensor package.

3. The stabilized platform of Claim 1, wherein second sensor package includes two level sensors for sensing a position of the payload platform in two perpendicular directions.

4. The stabilized platform of Claim 1, wherein the first sensor package is fixed with respect to the base.

5. The stabilized platform of Claim 1, wherein the first sensor package is mounted on the payload platform.

6. The stabilized platform of Claim 1, further comprising a camera mounted on the payload platform.

7. The stabilized platform of Claim 1, further comprising a chair mounted on the payload platform.

8. The stabilized platform of Claim 1, further comprising a table mounted on the payload platform.

9. The stabilized platform of Claim 1, wherein the stabilized platform is waterproof.

10. The stabilized platform of Claim 1, wherein the payload platform is rotated by three motors about three perpendicular axes of rotation.

11. The stabilized platform of Claim 10, wherein the first sensor package includes sensors for determining rotation about three perpendicular axes.

12. The stabilized platform of Claim 1, wherein the control system allows a user to set an initial payload platform position and provides self correction of the platform to the initial position.

13. The stabilized platform of Claim 1, wherein a universal camera mount is mounted on the payload platform and a camera is mounted on the camera

mount, the camera mount allowing hands on control of the camera by the operator and stabilization of the camera with the stabilized platform.

14. A method of stabilizing and self correcting a camera platform comprising:

positioning a stabilized camera platform on a moving vehicle;

stabilizing the platform in at least two dimensions based on information collected by a first sensor package sensing motion of the moving vehicle; and

self correcting a position of the platform based on information collected by a second sensor package mounted on the platform.

15. The method of Claim 14, wherein the information collected by the second sensor package is collected by a plurality of level sensors.

16. The method of Claim 14, wherein the stabilized platform is self corrected in two dimensions.

17. The method of Claim 14 further comprising controlling a camera mounted on the platform by hands on operator control.

18. An anti-seasickness chair comprising:

a stabilized platform configured to be mounted on a vehicle, the stabilized platform including sensors for sensing motion of the vehicle and a control system for compensating for motion of the vehicle in at least two dimensions; and

a chair mounted on the stabilized platform.

19. The anti-seasickness chair of Claim 18, wherein the stabilized platform is stabilized by a system of motors electronically controlled by the control system.

20. The anti-seasickness chair of Claim 18 wherein the stabilized platform is provided with platform sensors on the stabilized platform for self leveling of the platform.